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Experiment 1.10: Standing Waves on Strings

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I. EXPERIMENT 1.10: STANDING WAVES ON STRINGS

A. Abstract

Waves on a string under tension and fixed at both ends result in well-defined modes of vibration with a spectrum of frequencies given by the formula below

B. Formulas

$$f_n = n \left(\frac{v}{2L} \right), \quad n = 1, 2, 3, \dots \quad (1)$$

$$v = \sqrt{\frac{T}{\mu}} \quad (2)$$

where f_n is the frequency of the n^{th} standing wave mode on the string of length L , linear mass density μ , and under tension T , and v is the wave speed on the string.

C. Description and Background

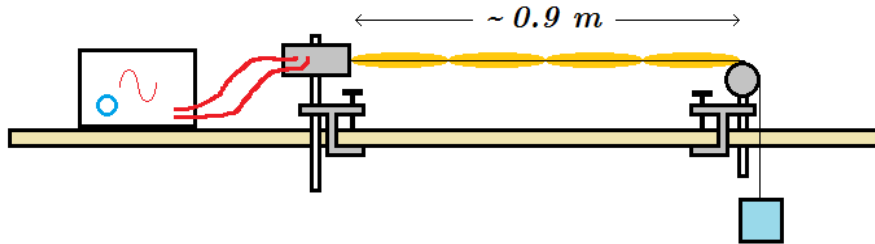


FIG. 1. Standing wave set-up.

The figure above shows the experimental set-up. An electro-mechanical device vibrates the end of a string of length, L , under tension. The tension is created by a weight, $T = Mg$, hanging over a pulley. The frequency of vibration is adjusted until an identifiable mode of standing wave is realized. In the figure, the mode has $n = 4$ anti-nodes (locations of large amplitude). In the experiment, this parameter will be fixed.

A sample segment of length, ℓ , and mass, m , is used to determine the linear mass density of the string, $\mu = m/\ell$. By combining Eqs. (1) and (2), one can derive the following relation between f_n^2 and M

$$f_n^2 = \frac{n^2 g}{4\mu L^2} M \quad (3)$$

In the experiment, the hanging mass is varied, and the frequency associated with $n = 4$ anti-nodes is determined experimentally. The data collected can then be analyzed. If the procedure is repeated numerous times, a linear regression analysis can be done and the slope, ς , of the best fit line to f_n^2 vs. M will equal

$$\varsigma = \frac{n^2 g}{4\mu L^2} = \frac{4g}{\mu L^2} \quad (4)$$

Because of the presence of g in this equation, it provides an indirect method of determining the acceleration due to gravity.

D. Procedure

1. Measure the length, ℓ , and mass, m , of a sample piece of string from the experiment.
2. Measure the length of the string (from vibrator to pulley), L , used to support the standing waves.
3. Attach a weight to the end of the string that hangs over the pulley and record its mass, M , in the measurement table.
4. Adjust the frequency of the sine wave generator so that a standing wave is set up with $n = 4$ anti-nodes. Record this frequency (f_n) in the measurement table.
5. Repeat steps 3 and 4 four more times with other weights.

E. Measurements

sample string mass, m [<i>gram</i>]	
sample string length, ℓ [<i>cm</i>]	

length of string under tension, $L = \underline{\hspace{2cm}}$ [*cm*]

Trial	M [<i>gram</i>]	f_4 [<i>Hz</i>]
1		
2		
3		
4		
5		

F. Instructions

1. Calculate the linear mass density of the string sample, μ .
2. Use the data and the equation for g implied by (4),

$$g = \frac{\mu L^2 f_4^2}{4M}$$

to complete the Plotting Table.

3. Use the Excel file provided, **StandingWavesLabPlot**, to plot f_4^2 vs. M (include the point (0,0) in the plot), and submit the plot as part of your work.
4. Use the slope, ς , of the regression line to determine the acceleration due to gravity, g_{slope} .
5. Based on the results in the table, what is \bar{g} ?
6. Determine the associated standard error, $\delta\bar{g}$.
7. What is the percent difference between \bar{g} and g_{slope} ?
8. During the semester, you have performed four experiments that either determined the acceleration due to gravity or whose results could have been used to determine it: The sphere drop, the inclined air-track and glider, the pendulum, and now standing waves on a string. Compare these four methods and make a case for which one is optimal if you conclude there is such a one.

G. Calculations

Plotting Table		
M [kg]	f_4^2 [Hz ²]	g [m/s ²]
0	0	N/A

$\mu = m/\ell$ [kg/m]	
f_4^2 vs. M : slope, ς [Hz ² /kg]	
g_{slope} [m/s ²]	
\bar{g} [m/s ²]	
$\delta\bar{g}$ [m/s ²]	
%-Diff (\bar{g}, g_{slope})	

Answer to 8 above: